

2550  
HW 9  
Solutions



①(a)

$$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ -2 & 4 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\text{So, } T(\vec{v}) = A\vec{v} \text{ where } A = \begin{pmatrix} 1 & 1 \\ -2 & 4 \end{pmatrix}.$$

Thus,  $T$  is a linear transformation

Note:  $A = [T]_{\gamma}$  where  $\gamma = [(1), (2)]$   
is the standard basis

①(b)

$$T \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1+1 \\ -2(1)+4(1) \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 0 \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$T \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1+2 \\ -2(1)+4(2) \end{pmatrix} = \begin{pmatrix} 3 \\ 6 \end{pmatrix} = 0 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 3 \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

Thus,

$$[T]_{\beta} = \left( [T(1)]_{\beta} \mid [T(2)]_{\beta} \right) = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$$

①(c)

$$\vec{v} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 2 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} - 1 \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\text{So, } [\vec{v}]_{\beta} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

Also,

$$T(\vec{v}) = T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} -1 \\ 2 \end{pmatrix} = 4\begin{pmatrix} 1 \\ 1 \end{pmatrix} - 3\begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

So,

$$[T(\vec{v})]_{\beta} = \begin{pmatrix} 4 \\ -3 \end{pmatrix}$$

And

$$[T]_{\beta} [\vec{v}]_{\beta} = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

$$= \begin{pmatrix} 2 \cdot 2 + 0(-1) \\ 0 \cdot 2 + 3(-1) \end{pmatrix} = \begin{pmatrix} 4 \\ -3 \end{pmatrix} = [T(\vec{v})]_{\beta}$$

$$\begin{aligned} \begin{pmatrix} 1 \\ 2 \end{pmatrix} &= a \begin{pmatrix} 1 \\ 1 \end{pmatrix} + b \begin{pmatrix} 1 \\ 2 \end{pmatrix} \\ \begin{pmatrix} -1 \\ 2 \end{pmatrix} &= \begin{pmatrix} a+b \\ a+2b \end{pmatrix} \\ a+b &= 1 \\ a+2b &= -2 \\ a &= 4, b = -3 \end{aligned}$$

①(d)

$$\vec{v} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ 1 \end{pmatrix} - 1 \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\text{So, } [\vec{v}]_{\beta} = \begin{pmatrix} 3 \\ -1 \end{pmatrix}$$

And,

$$\begin{aligned} T(\vec{v}) &= T\left(\begin{pmatrix} 2 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 2+1 \\ -2 \cdot 2 + 4 \cdot 1 \end{pmatrix} \\ &= \begin{pmatrix} 3 \\ 0 \end{pmatrix} = 6\begin{pmatrix} 1 \\ 1 \end{pmatrix} - 3\begin{pmatrix} 1 \\ 2 \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \begin{pmatrix} 2 \\ 1 \end{pmatrix} &= a \begin{pmatrix} 1 \\ 1 \end{pmatrix} + b \begin{pmatrix} 1 \\ 2 \end{pmatrix} \\ \begin{pmatrix} 3 \\ 0 \end{pmatrix} &= \begin{pmatrix} a+b \\ a+2b \end{pmatrix} \\ 2 = a+b &\rightarrow a = 3 \\ 1 = a+2b &\rightarrow b = -1 \end{aligned}$$

$$\text{So, } [T(\vec{v})]_{\beta} = \begin{pmatrix} 6 \\ -3 \end{pmatrix}$$

And,

$$[\tau]_{\beta} [\vec{v}]_{\beta} = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} 3 \\ -1 \end{pmatrix} = \begin{pmatrix} 2 \cdot 3 + 0(-1) \\ 0 \cdot 3 + 3(-1) \end{pmatrix}$$
$$= \begin{pmatrix} 6 \\ -3 \end{pmatrix} = [\tau(\vec{v})]_{\beta}$$

②(a)

$$T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x-y \\ x+y \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

So,  $T(\vec{v}) = A\vec{v}$  where  $A = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$ .

Thus,  $T$  is a linear transformation

②(b)

$$T\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \end{pmatrix} = 2 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 2 \cdot \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$
$$T\begin{pmatrix} -1 \\ 0 \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 0 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \end{pmatrix} = -1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 0 \cdot \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

I did these steps in my head since it was easy to solve

So,

$$[T]_{\beta} = \left( [T\begin{pmatrix} 1 \\ 1 \end{pmatrix}]_{\beta} \mid [T\begin{pmatrix} -1 \\ 0 \end{pmatrix}]_{\beta} \right) = \begin{pmatrix} 2 & -1 \\ 2 & 0 \end{pmatrix}$$

②(c)

$$\vec{v} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 0 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} - 1 \cdot \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

$$\text{So, } [\vec{v}]_{\beta} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

$$\text{And } T(\vec{v}) = T\begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 0 \cdot \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

$$\text{So, } [T(\vec{v})]_{\beta} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

Thus,

$$[T]_{\beta} [\vec{v}]_{\beta} = \begin{pmatrix} 2 & -1 \\ 2 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0+1 \\ 0+0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = [T(\vec{v})]_{\beta}$$

②(d)

$$\vec{v} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 1 \cdot \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

$$\text{So, } [\vec{v}]_{\beta} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\text{And } T(\vec{v}) = T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0-1 \\ 0+1 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} = 1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 2 \cdot \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

$$\text{So, } [T(\vec{v})]_{\beta} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

Thus,

$$[T]_{\beta} [\vec{v}]_{\beta} = \begin{pmatrix} 2 & -1 \\ 2 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2-1 \\ 2+0 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} = [T(\vec{v})]_{\beta}$$

(3)(a)

We have

$$T(\vec{a}) = T\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 3 \\ 0 \end{pmatrix} = \underbrace{3\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + 0\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + 0\begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}}_{3\vec{a} + 0\vec{b} + 0\vec{c}}$$

$$T(\vec{b}) = T\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -3 \\ 0 \\ 3 \end{pmatrix} = \underbrace{0\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + 3\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + 0\begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}}_{0\vec{a} + 3\vec{b} + 0\vec{c}}$$

$$T(\vec{c}) = T\begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 5 \\ 10 \\ 5 \end{pmatrix} = \underbrace{0\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + 0\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + 5\begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}}_{0\vec{a} + 0\vec{b} + 5\vec{c}}$$

Thus,

$$\begin{aligned} [T]_{\beta} &= \left( [T(\vec{a})]_{\beta} \quad | \quad [T(\vec{b})]_{\beta} \quad | \quad [T(\vec{c})]_{\beta} \right) \\ &= \begin{pmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{pmatrix} \end{aligned}$$

③(b)

Since  $\vec{v} = 1 \cdot \vec{a} + 1 \cdot \vec{b} + 1 \cdot \vec{c}$  we have  $[\vec{v}]_{\beta} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

Then

$$[T]_{\beta} [\vec{v}]_{\beta} = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \\ 5 \end{pmatrix}$$

And

$$T(\vec{v}) = T\left(\begin{pmatrix} 0 \\ 3 \\ 2 \end{pmatrix}\right) = \begin{pmatrix} 4 \cdot 0 + 2 \\ 2 \cdot 0 + 3 \cdot 3 + 2 \cdot 2 \\ 2 \cdot 0 + 4 \cdot 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 13 \\ 8 \end{pmatrix}$$

Note that

$$\begin{aligned} 3 \cdot \vec{a} + 3 \cdot \vec{b} + 5 \cdot \vec{c} &= 3 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + 3 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + 5 \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} \\ &= \begin{pmatrix} 2 \\ 13 \\ 8 \end{pmatrix} = T(\vec{v}) \end{aligned}$$

Thus,  $[T(\vec{v})]_{\beta} = \begin{pmatrix} 3 \\ 3 \\ 5 \end{pmatrix}$

$$\text{So, } [T]_{\beta} [\vec{v}]_{\beta} = [T(\vec{v})]_{\beta}.$$